

Optimal Transport and Applications

Summer School, Lake Arrowhead*

Oct 6th - Oct 11th 2013

Organizers:

Nestor Guillen

University of California, Los Angeles, USA

Dimitri Shlyakhtenko

University of California, Los Angeles, USA

Christoph Thiele

University of California, Los Angeles, USA / University of Bonn, Germany

*supported by NSF grand DMS 1001535

Contents

| | | |
|----------|--|-----------|
| 1 | Stability in the anisotropic isoperimetric inequality | 5 |
| | Marcos Charalambides, UC Berkeley | 5 |
| 1.1 | The anisotropic isoperimetric inequality | 5 |
| 1.2 | Gromov's proof revisited | 6 |
| 1.3 | From equality to near-equality | 8 |
| 1.4 | Stability in the Brunn-Minkowski inequality | 9 |
| 2 | Hölder regularity of optimal transport maps, and underlying inequalities from convex geometry | 11 |
| | Nick Cook, UCLA | 11 |
| 2.1 | Introduction | 11 |
| 2.2 | Geometric approach to Lemmas 1 and 4 | 13 |
| 3 | A convexity theory for interacting gases and equilibrium crystals | 17 |
| | Matías G. Delgadino, UMD | 17 |
| 3.1 | Introduction | 17 |
| 3.2 | Interpolation of Probability Measures | 17 |
| 3.3 | Displacement Convexity | 19 |
| | 3.3.1 Applications of Convexity | 20 |
| 4 | Differential equations methods for the Monge-Kantorovich mass transfer problem | 22 |
| | Taryn C Flock, UC Berkeley | 22 |
| 4.1 | Introduction | 22 |
| | 4.1.1 The Monge problem | 22 |
| | 4.1.2 The Monge-Kantorovich problem | 22 |
| | 4.1.3 The Monge-Kantorovich dual problem | 23 |
| | 4.1.4 Solving the Monge problem | 23 |
| 4.2 | The p-Laplacian | 24 |
| 4.3 | Sketch of the construction in [3] | 24 |
| 4.4 | Historical Remark | 26 |
| 5 | Benamou-Brenier's approach for OTT | 28 |
| | Augusto Gerolin, Università di Pisa | 28 |
| 5.1 | Introduction | 28 |

| | | |
|----------|--|-----------|
| 5.2 | Two Motivations | 29 |
| 5.3 | Heuristics | 30 |
| 5.4 | Euler Equation and Optimal Transport | 31 |
| 5.5 | Geodesic Spaces | 32 |
| 5.6 | Convex Reformulation of Benamou-Brenier | 33 |
| 5.6.1 | Dual Formulation | 34 |
| 6 | Polar Factorization and Monotone Rearrangement of Vector-Valued Functions | 36 |
| | Jordan Greenblatt, UCLA | 36 |
| 6.1 | Introduction | 36 |
| 6.2 | Monge-Kantorovich problems | 38 |
| 6.3 | Existence and uniqueness of solutions to the mixed MKP | 39 |
| 6.4 | Proof of polar factorization theorem | 40 |
| 7 | An Elementary Introduction to Monotone Transportation | 42 |
| | Paata Ivanisvili, MSU | 42 |
| 7.1 | Introduction | 42 |
| 7.2 | A construction of the Brenier Map | 43 |
| 7.3 | The Brunn–Minkowski Inequality | 44 |
| 7.4 | The Marton–Talagrand Inequality | 45 |
| 8 | A Priori Estimates and the Geometry of the Monge-Ampère Equation | 47 |
| | Sajjad Lakzian, CUNY | 47 |
| 8.1 | Introduction | 47 |
| 8.2 | Fully Nonlinear Uniformly Elliptic PDE | 47 |
| 8.3 | Caffrelli’s Main Results | 48 |
| 8.4 | Monge-Ampère Equation | 50 |
| 8.5 | Geometric Properties, Alexandrov Solutions and Localization | 50 |
| 8.6 | $C^{1,\alpha}$ Regularity | 52 |
| 8.7 | Sobolev Regularity | 53 |
| 9 | Partial differential equations and Monge-Kantorovich mass transport | 56 |
| | Tau Shean Lim, UW-Madison | 56 |
| 9.1 | Quick survey on Monge-Kantorovich problem | 56 |
| 9.2 | Case for $c(x, y) = \frac{1}{2} x - y ^2$ | 57 |

8 A Priori Estimates and the Geometry of the Monge-Ampère Equation

after L. Caffarelli

A summary written by Sajjad Lakzian

Abstract

We will very briefly touch on Caffarelli's regularity theory for fully nonlinear PDE and the geometry and regularity of the Monge-Ampère equation.

8.1 Introduction

The well known regularity results for small perturbation of linear equations are as follows:

(I) [Cordes-Nirenberg Type Estimates]. Let $0 < \alpha < 1$ and u a bounded solution on B_1 of $Lu = a_{ij}D_{ij}u = f$, $|a_{ij} - \delta_{ij}| \leq \delta_0(\alpha)$ small enough, and f bounded; then,

$$\|u\|_{C^{1,\alpha}(B_{1/2})} \leq C (\|u\|_{L^\infty(B_1)} + \|f\|_{L^\infty}). \quad (1)$$

(II) [Calderon-Zygmund]. if $f \in L^p$ for some $1 < p < \infty$ and $\delta_0(p)$ small enough, then

$$\|u\|_{W^{2,p}(B_{1/2})} \leq C (\|u\|_{L^\infty(B_1)} + \|f\|_{L^p}). \quad (2)$$

(III) [Schauder]. If a_{ij} and f are of class C^α then,

$$\|u\|_{C^{2,\alpha}(B_{1/2})} \leq C (\|u\|_{L^\infty(B_1)} + \|f\|_{C^\alpha}). \quad (3)$$

Caffarelli [1] has generalized these type of estimates to Fully nonlinear uniformly elliptic PDEs.

8.2 Fully Nonlinear Uniformly Elliptic PDE

The equation is of the form

$$F(D^2u, x) = f(x) \quad (4)$$

Uniform ellipticity in D^2 of equation 4 means that there exist λ and Λ such that for any matrix $N \in M_{n \times n}$ and any $N \in S^+$ we have

$$0 < \lambda\|M\| < F(N + M, x) - F(N, x) \leq \Lambda\|M\| \quad (5)$$

Definition 1 (Viscosity Solution). *The continuous function u is called a C^2 -viscosity solution of (4) if for any C^2 -subsolution (resp. supersolution) ϕ , $u - \phi$ cannot have an interior minimum (resp. maximum).*

Let S denote the symmetric matrices then, $\beta(x)$, the oscillation of F in the variable x is given by:

$$\beta(x) = \sup_{M \in S} \frac{F(M, x) - F(M, 0)}{\|M\|} \quad (6)$$

Caffarelli's results are as follows:

8.3 Caffarelli's Main Results

Theorem 2 ($W^{2,p}$ Regularity). *Let u be a bounded viscosity solution of $F(D^2u, x) = f(x)$ in B_1 and assume that solutions ω of the Dirichlet problem*

$$f(x) = \begin{cases} F(D^2u, x) = 0 & \text{in } B_r \\ \omega = \omega_0 & \text{in } \partial B_r \end{cases}$$

satisfy the interior apriori estimate

$$\|\omega\|_{C^{1,1}(B_{r/2})} \leq Cr^{-2} \|\omega\|_{L^\infty(\partial B_r)} \quad (7)$$

Let $n < p < \infty$ and assume that $f \in L^p$ and for some $\theta = \theta(p)$ sufficiently small

$$\sup_{B_1} \beta(x) \leq \theta(p) \quad (8)$$

Then $u|_{B_{1/2}}$ is in $W^{2,p}$ and

$$\|u\|_{W^{2,p}(B_{1/2})} \leq C \left(\sup_{\partial B_1} |u| + \|f\|_{L^p} \right). \quad (9)$$

Theorem 3 ($C^{1,\alpha}$ Regularity). *Assume that solutions ω to the equation*

$$F(D^2u, \omega) = 0 \quad (10)$$

in B_r satisfy the a priori estimate

$$\|\omega\|_{C^{1,\bar{\alpha}}(B_{r/2})} \leq Cr^{-(1+\bar{\alpha})} \|\omega\|_{L^\infty(B_r)} \quad (11)$$

Then for any $0 < \alpha < \bar{\alpha}$ there exists $\theta = \theta(\alpha)$ so that if

$$\int_{B_r} \beta^n(x) dx \leq \theta \quad (12)$$

and

$$\int_{B_r} |f(x)|^n dx \leq C_1 r^{(\alpha-1)n} \quad (13)$$

then any bounded solution u of

$$F(D^2u, x) = f(x) \quad (14)$$

in B_{r_0} is $C^{1,\alpha}$ at the origin. That is, there exist a linear function l such that for $r < r_0$

$$|u - l| \leq C_2 r^{1+\alpha} \quad (15)$$

and

$$\|l\|_{C^1} \leq C_3 \quad (16)$$

with

$$C_2, C_3 \leq C(\alpha) r_0^{-(1+\alpha)} \sup_{B_{r_0}} |u| + C_1^{1/n} \quad (17)$$

Theorem 4 ($C^{2,\alpha}$ Regularity). Assume the existence of $C^{2,\bar{\alpha}}$ interior a priori estimates for solutions of

$$F(D^2\omega + M, 0) = 0 \quad (18)$$

for any M satisfying

$$F(M, 0) = F(0, 0) = 0. \quad (19)$$

Then if $0 < \alpha < \bar{\alpha}$,

$$\int_{B_r} \beta^n dx \leq C r^{\alpha n}, \quad (20)$$

$$\int_{B_r} |f(x)|^n dx \leq C r^{\alpha n} \quad (21)$$

and u is a solution of $F(D^2u, x) = f(x)$, then, u is $C^{2,\alpha}$ at the origin (in the same sense as above).

These regularity results are proven by exploring Alexander-Bakelman-Pucci maximum principle and Krylov-Safanov Harnack's Inequality.

8.4 Monge-Ampère Equation

We will discuss the solutions to the Monge-Ampère equation, $\det D_{ij}u = f$ and $0 < \lambda_1 \leq f \leq \lambda_2 < \infty$ on a convex set Ω . MA equation is perhaps the most famous example of non-uniformly elliptic PDE.

8.5 Geometric Properties, Alexandrov Solutions and Localization

Solutions to the MA equation are invariant under *affine transformations* with the proper renormalization; i.e. if u is a solution and $TX = AX + B$ is an *affine transformation*, then

$$w = \frac{1}{(\det T)^{2/n}} u(TX) \quad (22)$$

is also a solution. This means that one may produce new solutions by "stretching" the graph of u in some directions and "squeezing" it in other directions (in a way that keeps the Jacobian of ∇u fixed) and hence producing singular solutions.

This fact also tells us that the estimates on the solutions are inevitably dependent on the geometry of the domain of the definition.

Definition 5 (Generalized (Alexandrov) Solutions). *Let ν be a Borel measure on Ω , an open and **convex** subset of \mathbb{R}^n . The convex function $u \in C(\Omega)$ is a generalized solution or Alexandrov solution to the MA equation*

$$\det D^2u = \nu \quad (23)$$

if the MA measure Mu equals ν . Mu is defined as follows:

$$Mu(E) = |\partial u(E)| \quad (24)$$

Remark 6. *For the MA equation $\det D^2u = f$, we take $\nu = f\mathcal{L}$ (\mathcal{L} : Lebesgue measure.)*

Proposition 7. *if f is continuous then every Alexandrov solution u is also a viscosity solution.*

Lemma 8. *If $u, v \in C(\bar{\Omega})$, $u|_{\partial\Omega} = v|_{\partial\Omega}$ and $v \geq u$ in Ω , then,*

$$\partial v(\Omega) \subset \partial u(\Omega) \quad (25)$$

Consequences of Lemma 8:

Theorem 9 (Alexandrov Maximum Principle). $u : \Omega \rightarrow \mathbb{R}$ convex and $u|_{\partial\Omega} = 0$ then,

$$|u(x)|^n \leq C_n(\text{diam}\Omega)^{n-1} \text{dist}(x, \partial\Omega) |\partial\Omega| \quad \forall x \in \Omega \quad (26)$$

Lemma 10 (Comparison Principle). Let u, v convex functions on open bounded convex Ω and $u \geq v$ on $\partial\Omega$. If $\det D^2u \leq \det D^2v$ (in the MA measure sense) then,

$$u \geq v \text{ in } \Omega \quad (27)$$

One key tool in studying MA equation is John's Lemma:

Lemma 11 (John's Lemma). For any open bounded convex set O , there exist an ellipsoid E such that

$$E \subset S \subset nE \quad (28)$$

hence, there exist an invertible orientation preserving affine transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that $T(S)$ is normalized i.e. $B_1 \subset T(S) \subset B_n$

One immediate consequence is the following: Let u is a strictly convex solution of MA inequality on Ω then for any $x \in \Omega' \subset\subset \Omega$ and t sufficiently small; Then, if T normalizes the section $S(x, p, t)$, then the normalization, u^* of u given by:

$$u^*(y) := (\det T)^{2/n} (u(T^{-1}(y)) - u(x) - p \cdot (T^{-1}(y) - x) - t) \quad (29)$$

solves the MA inequality on $T(S(x, p, t))$ with boundary condition $u^*|_{\partial T(S(x, p, t))} = 0$.

Lemma 12. Let Ω^* be a normalized open convex set i.e. $B_1 \subset \Omega^* \subset B_n$ and let u^* solve

$$\lambda_1 \leq \det D^2u \leq \lambda_2 \quad u^*|_{\partial\Omega^*} = 0 \quad (30)$$

(we call u^* a normalized solution) then, there constants c_1, c_2 depending on λ_1, λ_2 such that

$$0 < c_1 \leq \left| \inf_{\Omega^*} u^* \right| \leq c_2 \quad (31)$$

Proof. Apply Lemma 10 to $\omega_1 = \lambda_1(|x|^2 - 1)/2$ and $\omega_2 = \lambda_2(|x|^2 - n^2)/2$ \square

Another important result is the localization Theorem which will be used in the proof of compactness theorem and strict convexity of solutions.

Theorem 13 (Localization [2]). *Let u be a solution of **MA inequality** inside a convex set Ω , and let $l(x)$ is a supporting sloe to u . If the convex set*

$$W = \{u(x) = l(x)\} \quad (32)$$

contains more than one point (hence not strictly convex) then it can not have an extremal point in Ω (i.e. this set has to exit the domain of the definition).

As a consequence of Lemmas 13, we get the compactness for normalized solutions. [1]

The proof of regularity results uses the properties of the sections of the solutions i.e. the sets

$$S(x, p, t) := \{y \in \Omega : u(y) \leq u(x) + p \cdot (y - x) + t\} \text{ where, } p \in \partial u(x) \text{ and } t \geq 0. \quad (33)$$

the modulus of convexity is defined to be

$$\omega(x, u, t) := \sup_{p \in \partial u(x)} \text{diam} S(x, p, t) \quad (34)$$

and

$$\omega_{\Omega'} = \sup_{x \in \Omega'} \omega(x, u, t) \quad \Omega' \subset \subset \Omega \quad (35)$$

8.6 $C^{1,\alpha}$ Regularity

It is enough to prove the $C^{1,\alpha}$ regularity of renormalized solutions u with $\inf_{\Omega} u = u(x_0)$ and $u|_{\partial\Omega} = 0$. Let $C_{\beta} \subset \mathbb{R}^{n-1}$ be the cone with vertex $(x_0, u(x_0))$ and base $\{u = (1 - \beta)u(x_0)\}$. Suppose C_{α} is the graph of h_{α} .

Using the compactness result, one can find a universal δ for which

$$h_{1/2} \leq (1 - \delta)h_1 \quad (36)$$

After renormalizing the level surface $\{u = 2^{-k}\}$ and iteration, we get:

$$h_{2^{-k}} \leq (1 - \delta)^k h_1 \quad (37)$$

Since u is Lipschitz we have $h_1(x) \leq C|x-x_0|+u(x_0)$. Letting $2^{-\alpha'} = 1-\delta$ we get

$$h_{2^{-k}}(x) \leq C(2^{-k})^\alpha |x| \leq C2^{-k} \quad (38)$$

for $|x| \leq (2^{-k})^{(1-\alpha)}$

By the comparison Lemma 10, we have $u(x) \leq h_{2^{-k}}(x)$ as long as $h_{2^k}(x) \leq (1-2^{-k})u(x_0)$. This means that if for every x , we pick k that satisfies

$$\left(\frac{-C}{u(x_0)}\right)2^{-(k+1)(1-\alpha')} \leq |x-x_0| \leq \left(\frac{-C}{u(x_0)}\right)2^{-k(1-\alpha')} \quad (39)$$

then,

$$h_{2^k}(x) \leq (1-2^{-k})u(x_0) \quad (40)$$

And direct computation gives:

$$u(x) - u(x_0) \leq C|x-x_0|^{1+\alpha} \text{ where, } \alpha = \frac{\alpha'}{1-\alpha'} \quad (41)$$

This shows that for all supporting planes l_{x_0} , we have:

$$\sup_{B(x_0,r)} |u(x) - l_{x_0}(x)| \leq Cr^{1+\alpha} \quad (42)$$

and this will imply that u is $C^{1,\alpha}$.

8.7 Sobolev Regularity

Theorem 14 (Caffarelli [1]). *Let u be a convex viscosity solution of the MA equation on a normalized convex set Ω and $u|_{\partial\Omega} = 0$ then,*

(I) $\forall p < \infty, \exists \epsilon = \epsilon(p)$ s.t. if

$$|f - 1| \leq \epsilon \quad (43)$$

then,

$$u \in W^{2,p}(B_{1/2}) \quad (44)$$

and

$$\|u\|_{W^{2,p}(B_{1/2})} \leq C(\epsilon) \quad (45)$$

(II) *If $f > 0$ and is continuous, then $u \in W^{2,p}(B_{1/2})$ for any $p < \infty$ and*

$$\|u\|_{W^{2,p}(B_{1/2})} \leq C(p, \sigma) \quad (46)$$

where σ is the modulus of continuity of f .

A consequence is the following theorem:

Theorem 15. $f \in C^\alpha \implies u \in C^{2,\alpha}$

Main Ideas of the Proof:

Lets consider a particular case: $1 \leq \det D_{ij}u \leq 1 + \epsilon(p)$ and we want to prove that $\|u\|_{W^{2,p}(B_{1/2})} \leq C(p)$.

Step 1 Take the section $S_{\mu,L} = \{u - L \leq \min(u - L) + \mu\}$ and normalize it by T_μ . Then approximate (using an approximation lemma as in [1]) the normalization of $u - L$ by solutions of $\det D_{ij}\omega = 1$. Notice that ω is $C^{2,\alpha}$

Step 2 Iterating this approximation at diadic levels $\mu = 2^{-k}$, one can show that

$$T_m u = D_\mu \tilde{T}_m u \quad (47)$$

where $D_m u = \left(\frac{1}{2^\mu}\right)^{1/2}$ Id is a dilation and $\tilde{T}_m u$ is a transformation of norm

$$\|\tilde{T}_\mu\|, \|\tilde{T}_m u^{-1}\| \leq \mu^{-\sigma} \quad (48)$$

with $\sigma = \sigma(\epsilon)$ is as small as we want.

So far we have a normalized solution u on $T_\mu(S_{\mu,L})$ with the following properties:

(a) $1 \leq \det D_{ij}u \leq 1 + \epsilon$. (b) $\{u = 1\}$ is trapped between B_1 and B_n . (c) u is ϵ away from the $C^{2,\alpha}$ approximation function ω that solves $\det D_{ij}\omega = 1$ and $\{\omega = 0\} = \{u = 0\}$

Step 3

Lemma 16. Let $\Gamma(u - \frac{1}{2}\omega)$ be the convex envelope of $u - \frac{1}{2}\omega$, then, the contact set $C = \{\Gamma(u - \frac{1}{2}\omega) = u - \frac{1}{2}\omega\}$ satisfies:

$$\frac{|B_{1/2} \cap C|}{|B_{1/2}|} \geq 1 - C\epsilon^{1/2} \quad (49)$$

in other words, the contact points cover as large a portion of $B_{1/2}$ as we want.

Corollary 17. At any contact point x_0 , there exist a plane L_{x_0} such that in all of Ω

$$L_{x_0}(x) \leq (u - \frac{1}{2}\omega)(x) \text{ and } L_{x_0}(x_0) = (u - \frac{1}{2}\omega)(x_0) \quad (50)$$

which means that for any contact point x_0 , u has a tangent paraboloid by below of the form

$$L_{x_0} + \frac{1}{N}|x - x_0|^2 \tag{51}$$

Remark 18. If u has a tangent paraboloid by below $u \geq \frac{1}{\lambda}|x|^2$ then u has a tangent paraboloid by above $u \leq \lambda^{n-1}|x|^2$ because one can see that a paraboloid from below puts a uniform bound $\|T_\mu\| \leq \lambda$ then since $\det \tilde{T}_m u = 1$, we also get a bound by below.

Step 4 having controlled tangent paraboloids from above and below $\implies W^{2,p}$ estimates.

References

- [1] Caffarelli, L. A, *A priori estimates and the geometry of the Monge Ampère equation.* IAS/Park City Math. Ser. **2** (1996), no. 1, 5–63;
- [2] Caffarelli, L. A, *A localization property of viscosity solutions to the Monge-Ampère equation and their strict convexity.* Ann. of Math. **131** (1990), no. 1, 129–134;